

Absolute encoders - bus interfaces

Solid shaft $\varnothing 11$ mm with EURO flange B10

CANopen® / 13 bit ST / 16 bit MT / Speed switch

PMG10 - CANopen®



PMG 10 - picture similar

Technical data - electrical ratings

Voltage supply	10...30 VDC
Short-circuit proof	Yes
Consumption w/o load	≤ 200 mA
Initializing time	≤ 500 ms after power on
Interface	CANopen®
Function	Multiturn
Transmission rate	10...1000 kBaud
Device address	Rotary switch in bus connecting box (type-specific)
Steps per turn	8192 / 13 bit
Number of turns	65536 / 16 bit
Additional outputs	Square-wave HTL/TTL (RS422)
Sensing method	Magnetic
Interference immunity	EN 61000-6-2
Emitted interference	EN 61000-6-3
Programmable parameters	Steps per revolution Number of revolutions Preset, scaling, rotating direction
Diagnostic function	Position or parameter error
Status indicator	DUO-LED in bus connecting box 4 LEDs in device back side
Approval	CE

Technical data - electrical ratings (speed switches)

Interface	RS485
Switching accuracy	± 2 % (or Digit)
Switching outputs	1 output (Open-Collector or Solid State Relay)
Output switching capacity	30 VDC; ≤ 100 mA
Switching delay time	≤ 20 ms

Features

- Interface CANopen®
- Magnetic sensing method
- Resolution: singleturn 13 bit, multiturn 16 bit
- Function display via LEDs
- Multiturn sensing with Energy Harvesting technologie, without gear or battery
- Two hybrid bearings, one at each end
- Special protection against corrosion C5-M

Optional

- Integrated speed switch, programmable
- Additional output incremental with zero pulse

Technical data - mechanical design

Size (flange)	$\varnothing 115$ mm
Shaft type	$\varnothing 11$ mm solid shaft
Flange	EURO flange B10
Protection DIN EN 60529	IP 66/IP 67
Operating speed	≤ 6000 rpm
Range of switching speed	± 2 ...6000 rpm, default 6000 rpm
Operating torque typ.	10 Ncm
Rotor moment of inertia	1 kgcm ²
Admitted shaft load	≤ 450 N axial ≤ 650 N radial
Materials	Housing: aluminium alloy Shaft: stainless steel
Operating temperature	-40...+85 °C
Relative humidity	95 % non-condensing
Resistance	IEC 60068-2-6 Vibration 30 g, 10-2000 Hz IEC 60068-2-27 Shock 400 g, 1 ms
Corrosion protection	IEC 60068-2-52 Salt mist Complies to ISO 12944-5:1998 Protective paint systems (C5-M)
Weight approx.	2.7 kg (depending on version)
Connection	Bus connecting box Terminal box incremental

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Part number

PMG10

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Additional output *

0 Without

See also table "Additional output **"

Resolution multiturn

0 Without

6 16 bit

Voltage supply / interface

C6 10...30 VDC, CANopen® (DS 406)

Connection

- 5 1x bus connecting box with 3 cable glands M16, radial
- 1 1x bus connecting box with 2 connectors M12, radial
- F 1x bus connecting box with 3 cable glands M16, radial + 1x terminal box with 1 cable gland M20, radial
- Z 1x bus connecting box with 2 connectors M12, radial + 1x terminal box with 1 cable gland M20, radial

Shaft diameter

1 $\varnothing 11$ mm with key 4 mm

Protection

- D IP 66 and IP 67, optimized for dusty environments
- L IP 66 and IP 67, optimized for oily and wet environments

Flange

H EURO flange B10, shaft insulation hybrid bearing

Speed switch / Programming

Without

- D With speed switch *
(Standard: Open Collector, Solid State Relais on request)

* Only for connection F or Z

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Part number - tables

Additional output *

0	(Without)
Q	(8192 ppr TTL/HTL push-pull (Vin=Vout), 6 channels)
P	(8192 ppr TTL (RS422), 6 channels)
G	(5000 ppr TTL/HTL push-pull (Vin=Vout), 6 channels)
H	(5000 ppr TTL (RS422), 6 channels)
K	(4096 ppr TTL/HTL push-pull (Vin=Vout), 6 channels)
J	(4096 ppr TTL (RS422), 6 channels)
7	(3072 ppr TTL/HTL push-pull (Vin=Vout), 6 channels)
8	(3072 ppr TTL (RS422), 6 channels)
9	(2048 ppr TTL/HTL push-pull (Vin=Vout), 6 channels)
4	(2048 ppr TTL (RS422), 6 channels)
5	(1024 ppr TTL/HTL push-pull (Vin=Vout), 6 channels)
6	(1024 ppr TTL (RS422), 6 channels)
1	(512 ppr TTL/HTL push-pull (Vin=Vout), 6 channels)
2	(512 ppr TTL (RS422), 6 channels)

Accessories

Mounting accessories

K 35	Spring washer coupling for solid shaft $\varnothing 6...12$ mm
K 50	Spring washer coupling for solid shaft $\varnothing 11...16$ mm
K 60	Spring washer coupling for solid shaft $\varnothing 11...22$ mm

Absolute encoders - bus interfaces

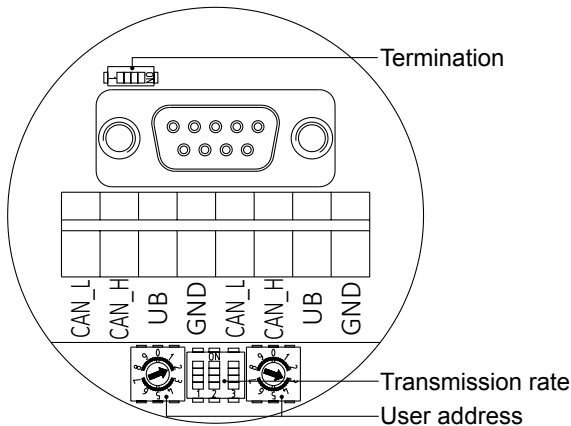
Solid shaft $\varnothing 11$ mm with EURO flange B10

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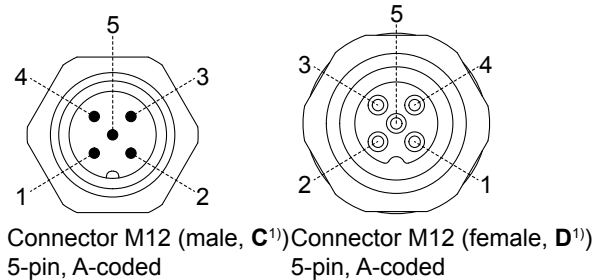
CANopen® - Terminal assignment

View A¹⁾ - View inside bus cover



View C¹⁾ / View D¹⁾ - View into connector

male / female	Connection	Description
1	GND	Ground for UB
2	UB	Voltage supply 10...30 VDC
3	GND	Ground for UB
4	CAN_H	CAN Bus signal (dominant HIGH)
5	CAN_L	CAN Bus signal (dominant LOW)

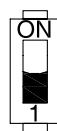


Terminals of the same significance are internally connected and identical in their functions. Max. load on the internal terminal connections UB-UB and GND-GND is 1 A each.

CANopen® - Features

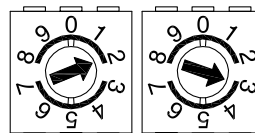
Bus protocol	CANopen®
CANopen®-Features	Device Class 2 CAN 2.0B
Device profile	CANopen® CiA DSP 406, V 3.0
Operating mode	Polling mode (asynch, via SDO) Cyclic mode (asynch-cyclic) Synch mode (synch-cyclic) Acyclic mode (synch-acyclic)
Diagnosis	The encoder supports the following error warnings: - Position error
Default settings	User address 00

CANopen® - Termination



ON = final user
OFF = user x

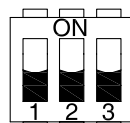
CANopen® - User address



Defined by rotary switch.
Example: User address 23

CANopen® - Transmission rate

Transmission rate	Dip switch position		
	1	2	3
10 kBaud	OFF	OFF	OFF
20 kBaud	OFF	OFF	ON
50 kBaud*	OFF	ON	OFF
125 kBaud	OFF	ON	ON
250 kBaud	ON	OFF	OFF
500 kBaud	ON	OFF	ON
800 kBaud	ON	ON	OFF
1000 kBaud	ON	ON	ON



* Default

¹⁾ See dimensions

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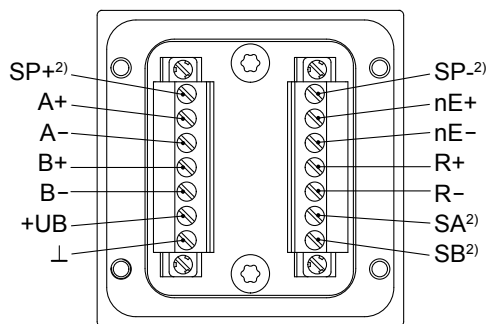
PMG10 - CANopen®

Speed switch/incremental - Terminal significance

+UB	Voltage supply
⊥	Ground
A+	Channel A+
A-	Channel A- (channel A+ inverted)
B+	Channel B+
B-	Channel B- (channel B+ inverted)
R+	Zero pulse (reference signal)
R-	Zero pulse inverted
nE+	System OK+ / error output
nE-	System OK- / error output inverted
SP+ ²⁾	DSL_OUT1 / speed switch (Open-Collector or Solid State Relay)
SP- ²⁾	DSL_OUT2 / speed switch (0 V or Solid State Relay)
SA ²⁾	RS485+ / programming interface
SB ²⁾	RS485- / programming interface

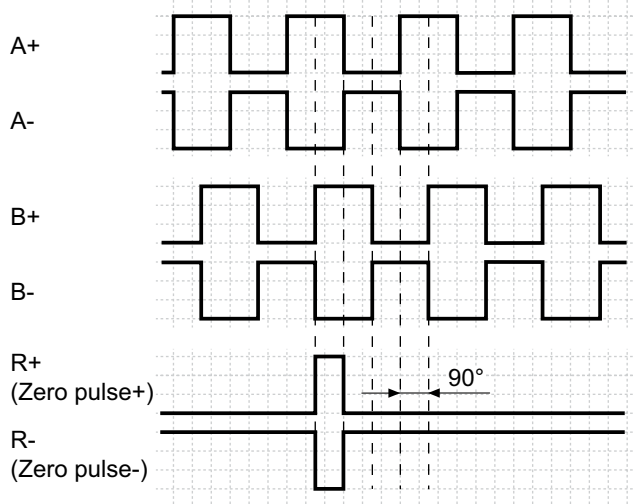
Speed switch/incremental - Terminal assignment terminal box

View B¹⁾

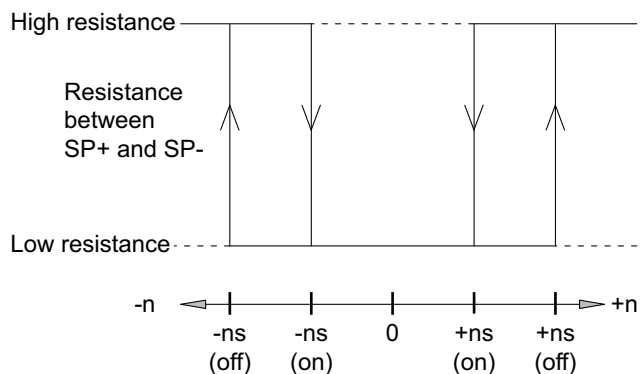


Incremental - Output signals

Version with additional incremental output at positive rotating direction



Speed switch - Switching characteristics



- n = Speed
- $+ns$ (on) = Activation speed at shaft rotation in positive rotating direction¹⁾.
- $+ns$ (off) = Deactivation speed at shaft rotation in positive rotating direction¹⁾.
- $-ns$ (on) = Activation speed at shaft rotation in negative rotating direction¹⁾.
- $-ns$ (off) = Deactivation at shaft rotation in negative rotating direction¹⁾.

¹⁾ See dimensions

²⁾ Do not use at version without speed switch

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Dimensions

